

Figure: Tanks A and B containing salt

Consider system of equations:

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$$\mathbf{x}'(t) = \mathbf{P}(t)\mathbf{x}(t) + \mathbf{g}(t).$$

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## Linear independence

For the homogeneous problem

$$\mathbf{x}'(t) = \mathbf{P}(t)\mathbf{x}(t)$$

analogously to second order odes, if we can find  $\{\mathbf{x}_i\}_{i=1}^n$  s.t.

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#### General solution

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and for tank B we must also subtract the draining of salt from pipe OP

$$\frac{\mathrm{d}y}{\mathrm{d}t} = \mathsf{Input} \; \mathsf{rate} - \mathsf{Output} \; \mathsf{rate} = 1 \cdot \frac{x(t)}{1000} - 2 \cdot \frac{y(t)}{1000} - 1 \cdot \frac{y(t)}{1000}.$$

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In matrix form our system is

$$\binom{x'}{y'} = \frac{1}{1000} \begin{bmatrix} -1 & 2\\ 1 & -3 \end{bmatrix} \binom{x}{y}.$$

First we compute the eigenvalues

$$\det \begin{bmatrix} -1 - \lambda & 2\\ 1 & -3 - \lambda \end{bmatrix} = 0 \quad \Rightarrow (-1 - \lambda)(-3 - \lambda) - 2 \cdot 1 = 0$$
$$\Rightarrow \lambda_1 = -2 + \sqrt{3}, \ \lambda_2 = -2 - \sqrt{3}.$$

Second we find the corresponding eigenvectors. To find  $\xi_1 := \begin{pmatrix} \xi_{1,1} \\ \xi_{2,1} \end{pmatrix}$  we solve the system (up to multiples):

$$\begin{bmatrix} -1-\lambda_1 & 2\\ & \\ 1 & -3-\lambda_1 \end{bmatrix} \begin{pmatrix} \xi_{1,1}\\ \xi_{2,1} \end{pmatrix} = \begin{pmatrix} 0\\ 0 \end{pmatrix}.$$

By solving the system directly we obtain the solution (up to multiples). For example, we rewrite the above to get:

$$\begin{cases} (1-\sqrt{3})\xi_{1,1}+2\xi_{2,1}=0\\\\\xi_{1,1}+(-1-\sqrt{3})\xi_{2,1}=0 \end{cases} \implies \xi_1 = \binom{\xi_{1,1}}{\xi_{2,1}} = \binom{1+\sqrt{3}}{1}.$$

Similarly to obtain  $\boldsymbol{\xi}_2$  we have to solve

$$\begin{bmatrix} -1 - (-2 - \sqrt{3}) & 2 \\ 1 & -3 - (-2 - \sqrt{3}) \end{bmatrix} \begin{pmatrix} \xi_{1,2} \\ \xi_{2,2} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

and we get

$$\boldsymbol{\xi}_2 = \begin{pmatrix} 1 - \sqrt{3} \\ 1 \end{pmatrix}.$$

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Therefore, by the discussion above the general solution will be

$$\mathbf{x}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \frac{1}{1000} c_1 \cdot \boldsymbol{\xi}_1 e^{\lambda_1 t} + \frac{1}{1000} c_2 \cdot \boldsymbol{\xi}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} = c_1 \cdot \begin{pmatrix} 1 + \sqrt{3} \\ 1 \end{pmatrix} \frac{e^{(-2+1)t}}{1000} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} e^{-2t} \mathbf{x}_2 e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} \mathbf{x}_2 e^{\lambda_2 t} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} \mathbf{x}_2 e^{\lambda_2 t} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} e^{\lambda_2 t} e^{-2t} \mathbf{x}_2 e^{\lambda_2 t} e^{\lambda_2 t} e^{\lambda_2 t} e^{\lambda_2 t} e^{\lambda_2 t} \mathbf{x}_2 e^{\lambda_2 t} e^{\lambda_2 t}$$

Since 2 > √3, both the eigenvalues are negative and in turn the salt concentrations x(t), y(t) will go to zero as t → +∞. This is reasonable because through pipe IP we are injecting salt-free water that over time transports the tanks' salt out through pipe OP.
Next we study the stability. Since -2 + √3 > -2 - √3, we get e<sup>(-2+√3)t</sup> > e<sup>(-2-√3)t</sup> and so as t → +∞ the first eigenvector (<sup>1+√3</sup>) will dominate.



# The End

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