## Repeated eigenvalues

2 nonhomogeneous linear first ord



Figure: repeated eigenvalue

## Repeated eigenvalues

$$\mathbf{x}' = \begin{bmatrix} 1 & -1 \\ 1 & 3 \end{bmatrix} \mathbf{x}$$

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1 We first find the eigenvalues:

$$\lambda = \frac{\mathsf{Tr}(\mathbf{A})}{2} \pm \frac{1}{2}\sqrt{\mathsf{Tr}(\mathbf{A})^2 - 4\det(\mathbf{A})} = 2$$

and so we have a repeated eigenvalue.

2 Second, we find the corresponding eigenvector:

$$\begin{bmatrix} 1-\lambda & -1\\ 1 & 3-\lambda \end{bmatrix} \begin{pmatrix} \xi_1\\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0\\ 0 \end{pmatrix} \Longrightarrow \boldsymbol{\xi} = \begin{pmatrix} \xi_1\\ \xi_2 \end{pmatrix} = \begin{pmatrix} 1\\ -1 \end{pmatrix}.$$

• Assuming that  $\mathbf{x}_2 := \boldsymbol{\xi} e^{\lambda t} \cdot t$  fails because it implies  $\xi = 0$ .

**3** Assuming the solution is of the form  $\mathbf{x}_2 := \boldsymbol{\xi} e^{\lambda t} \cdot t + \eta e^{\lambda t}$  and plugging into our ODE we obtain:

$$(\mathbf{A} - \lambda \mathbf{I}_2)\boldsymbol{\eta} = \boldsymbol{\xi} \Longrightarrow \begin{bmatrix} 1 - \lambda & -1 \\ 1 & 3 - \lambda \end{bmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

Solving this system gives us:

$$\eta_1 + \eta_2 = -1 \Longrightarrow \boldsymbol{\eta} = \binom{k}{-k-1} = k \binom{1}{-1} + \binom{0}{-1},$$

where k is any real number. We can rewrite  $\eta$  as:

$$oldsymbol{\eta} = koldsymbol{\xi} + egin{pmatrix} 0 \ -1 \end{pmatrix}$$

Therefore, the general solution is:

$$\begin{aligned} \mathbf{x} &= c_1 \mathbf{x}_1 + c_2 \mathbf{x}_2 \\ &= c_1 e^{2t} \boldsymbol{\xi} + c_2 (\boldsymbol{\xi} e^{2t} \cdot t + \boldsymbol{\eta} e^{2t}) \\ &= c_1 e^{2t} \boldsymbol{\xi} + c_2 \left[ \boldsymbol{\xi} e^{2t} \cdot t + \left\{ k \boldsymbol{\xi} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right\} e^{2t} \right] \\ &= e^{2t} \left[ (c_1 + kc_2) \begin{pmatrix} 1 \\ -1 \end{pmatrix} + c_2 \left\{ \begin{pmatrix} 1 \\ -1 \end{pmatrix} t + \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right\} \right]. \end{aligned}$$

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The vector  $\boldsymbol{\xi}_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  dominates the long term behaviour due to the extra term  $\begin{pmatrix} 1 \\ -1 \end{pmatrix} t$  (provided we do not choose  $c_2 = 0$ ). So we see that, essentially, all solutions are diverging away from the linear span of  $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$ .



MAT244 Ordinary Differential Equations

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• By determining  $\eta$  we obtain:

$$\mathbf{x} = c_1 \mathbf{x}_1 + c_2 \mathbf{x}_2 = c_1 \boldsymbol{\xi} e^{\lambda t} + c_2 (\boldsymbol{\xi} e^{\lambda t} \cdot t + \boldsymbol{\eta} e^{\lambda t}).$$

$$\mathbf{x}' = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix} \mathbf{x} - \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Find  $\eta$  from

$$(\mathbf{A} - \lambda \mathbf{I}_2)\boldsymbol{\eta} = \boldsymbol{\xi}.$$

Then

$$\mathbf{x} = c_1 \mathbf{x}_1 + c_2 \mathbf{x}_2 = c_1 \boldsymbol{\xi} e^{\lambda t} + c_2 (\boldsymbol{\xi} e^{\lambda t} \cdot t + \boldsymbol{\eta} e^{\lambda t}).$$

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$$\mathbf{x}' = \begin{bmatrix} 1 & -4 \\ 4 & -7 \end{bmatrix} \mathbf{x}, \mathbf{x} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$

Find  $\eta$  from

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Then

$$\mathbf{x} = c_1 \mathbf{x}_1 + c_2 \mathbf{x}_2 = c_1 \boldsymbol{\xi} e^{\lambda t} + c_2 (\boldsymbol{\xi} e^{\lambda t} \cdot t + \eta e^{\lambda t}).$$

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Consider nonhomogeneous linear first order systems:

$$\mathbf{x}' = \mathbf{A}\mathbf{x} + \mathbf{g}(t),$$

where g(t) is a vector of continuous functions and A is a diagonalizable  $n \times n$  matrix with eigenvalues  $\{\lambda_i\}_{i=1,...,n}$ . The latter assumption means that if T has the eigenvectors of A as columns, then  $T^{-1}AT = D$  is a diagonal matrix.

Plugging in  $\mathbf{x} = \mathbf{T}\mathbf{y}$  for some yet unknown  $\mathbf{y}$  we obtain

$$\mathbf{T}\mathbf{y}' = \mathbf{x}' = \mathbf{A}\mathbf{x} + \mathbf{g}(t) = \mathbf{A}\mathbf{T}\mathbf{y} + \mathbf{g}(t)$$
  
 $\implies \mathbf{y}' = \mathbf{T}^{-1}\mathbf{A}\mathbf{T}\mathbf{y} + \mathbf{T}^{-1}\mathbf{g}(t) = \mathbf{D}\mathbf{y} + \mathbf{T}^{-1}\mathbf{g}(t).$ 

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As a result, we decoupled the system. From this decoupled system we obtain the first order equations:

$$y'_i = \lambda_i y_i(t) + (\mathbf{T}^{-1}\mathbf{g}(t))_i$$
 for  $i = 1, ..., n$ .

For  $h_i(t) := (\mathbf{T}^{-1}\mathbf{g}(t))_i$  we have (by the method of integrating factors)

$$y_i(t) = e^{\lambda_i t} \left[ \int_0^t e^{-\lambda_i s} h_i(s) ds + c_i \right].$$

Therefore, we found the solution  $\mathbf{x} = \mathbf{T}\mathbf{y}$ .

## The End

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