

1 Variation of parameters

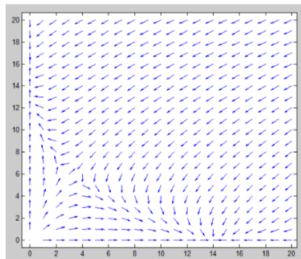


Figure: competing species separatrix

General nonhomogeneous systems

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where $P(t)$ is a matrix that also depends on time.

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where $P(t)$ is a matrix that also depends on time. We make the ansatz

$$\mathbf{x}(t) = \Psi(t)\mathbf{y}(t),$$

where Ψ is a matrix whose columns are the x_1, x_2 solutions for the homogeneous problem.

Variation of parameters: system to solve

Plugging in the ansatz we obtain:

$$\Psi(t)y'(t) = g(t).$$

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or equivalently

$$\begin{cases} x_{1,1}(t)v_1' + x_{1,2}(t)v_2' = g_1(t) \\ x_{2,1}(t)v_1' + x_{2,2}(t)v_2' = g_2(t) \end{cases}$$

Example

Consider the system

$$\mathbf{x}'(t) = \begin{bmatrix} 1 & 1 \\ 4 & -2 \end{bmatrix} \mathbf{x} + \begin{pmatrix} e^{-2t} \\ -2e^t \end{pmatrix}.$$

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$$\mathbf{x}'(t) = \begin{bmatrix} 4 & -2 \\ 8 & -4 \end{bmatrix} \mathbf{x} + \begin{pmatrix} t^{-3} \\ -t^{-2} \end{pmatrix}.$$

- ① First we find the fundamental matrix Ψ : the eigenvalue is $(0, \begin{pmatrix} 1 \\ 2 \end{pmatrix})$ and $\eta = k\begin{pmatrix} 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \end{pmatrix}$, therefore, the solution is

$$\mathbf{x}(t) = c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 \left(t \begin{pmatrix} 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right) \Rightarrow$$
$$\Psi(t) = \begin{bmatrix} 1 & t \\ 2 & 2t - 1 \end{bmatrix}.$$

- ② The system is

$$\begin{cases} v_1' + tv_2' = t^{-3} \\ 2v_1' + (2t - 1)v_2' = -t^{-2} \end{cases}$$

and we obtain

$$\mathbf{v}'(t) = \begin{pmatrix} -(t^{-1} + 2t^{-2} - t^{-3}) \\ t^{-2} + 2t^{-3} \end{pmatrix} \Rightarrow$$

$$\mathbf{v}(t) = \begin{pmatrix} \frac{4t-1}{2t^2} - \log(t) \\ -\frac{t+1}{t^3} \end{pmatrix}.$$

Therefore, the nonhomogeneous solution is

$$\begin{aligned} \mathbf{x}_{nh}(t) &= \Psi(t)\mathbf{v}(t) \\ &= \begin{bmatrix} 1 & t \\ 2 & 2t-1 \end{bmatrix} \begin{pmatrix} \frac{4t-1}{2t^2} - \log(t) \\ -\frac{t+1}{t^3} \end{pmatrix} \\ &= \begin{pmatrix} -\frac{1+t}{t^2} + \frac{-1+4t}{2t^2} - \log(t) \\ -\frac{((1+t)(-1+2t))}{t^3} + 2\left(\frac{-1+4t}{2t^2} - \log(t)\right) \end{pmatrix} \\ &= -\log(t) \begin{pmatrix} 1 \\ 2 \end{pmatrix} + t^{-2} \begin{pmatrix} -3/2 \\ -2 \end{pmatrix} + t^{-1} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + t^{-3} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{aligned}$$

The general solution is

$$\mathbf{x}(t) = c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 \left(\begin{pmatrix} 1 \\ 2 \end{pmatrix} t - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right) + \mathbf{x}_{nh}(t).$$

In class example

Consider the system

$$\mathbf{x}'(t) = \begin{bmatrix} -1 & -1 \\ 1 & -3 \end{bmatrix} \mathbf{x} + \begin{pmatrix} e^{-2t} \\ -2e^t \end{pmatrix}.$$

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