

# ECO 3901

## EMPIRICAL INDUSTRIAL ORGANIZATION

### Lecture 3

#### Structural Estimation of Dynamic Games

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## Lecture 3: Structural Estimation of Dynamic Games

## Outline

### 1. Full Solution Methods

- [1.1.] Nested Fixed Point algorithm (NFXP)
- [1.2.] MPEC
- [1.3.] Nested Pseudo Likelihood (NPL)

### 2. Two-step CCP methods

## Estimation Methods

- The primitives of the model,  $\{\pi_i, \beta_i, F_x, G_\varepsilon : i \in \mathcal{I}\}$ , can be described in terms of a vector of structural parameters  $\theta$  that is unknown to the researcher.
- We study methods for the estimation of  $\theta$ .
- It is convenient to distinguish three components in the vector of structural parameters:  $\theta = (\theta_\pi, \theta_f, \beta)$ .
- **Full Solution Methods** impose the equilibrium restrictions in the estimated structural parameters  $(\hat{\theta})$  and CCPs  $(\hat{\mathbf{P}})$ :

$$\hat{\mathbf{P}} = \Psi(\hat{\theta}, \hat{\mathbf{P}})$$

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# 1. Full Solution Methods

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## MLE-NFXP with equilibrium uniqueness

- Rust (1987) NFXP algorithm is a gradient method to obtain MLE.
- Originally proposed for single-agent models, it has been applied to the estimation of games with unique equilibrium for every  $\theta$ .
- Let  $\{P_i(a_i|\mathbf{x}, \theta) : i \in \mathcal{I}\}$  be the equilibrium CCPs associated with  $\theta$ . The **full log-likelihood function** is:  $\ell(\theta) = \sum_{m=1}^M \ell_m(\theta)$ , where  $\ell_m(\theta)$  is the contribution of market  $m$ :

$$\ell_m(\theta) = \sum_{i=1}^N \sum_{t=1}^T \log P_i(a_{imt}|\mathbf{x}_{mt}, \theta) + \log f_x(\mathbf{x}_{m,t+1}|\mathbf{a}_{mt}, \mathbf{x}_{mt}, \theta_f)$$

## MLE-NFXP with equilibrium uniqueness [2]

- NFXP combines BHHH iterations (**outer algorithm**) with equilibrium solution algorithm (**inner algorithm**) for each trial value  $\theta$ .
- A BHHH iteration is:

$$\hat{\theta}_{k+1} = \hat{\theta}_k + \left( \sum_{m=1}^M \frac{\partial \ell_m(\hat{\theta}_k)}{\partial \theta} \frac{\partial \ell_m(\hat{\theta}_k)}{\partial \theta'} \right)^{-1} \left( \sum_{m=1}^M \frac{\partial \ell_m(\hat{\theta}_k)}{\partial \theta} \right)$$

- The score vector  $\partial \ell_m(\hat{\theta}_k) / \partial \theta$  depends on  $\partial \log P_i(a_{imt} | \mathbf{x}_{mt}, \hat{\theta}_k) / \partial \theta$ . To obtain these derivatives, the inner algorithm of NFXP solves for the equilibrium CCPs given  $\hat{\theta}_k$ .

## MLE-NFXP with multiple equilibria

- With Multiple Equilibria,  $\ell_m(\theta)$  is not a function but a correspondence.
- To define the MLE in a model with multiple equilibria, it is convenient to define an *extended* or **Pseudo Likelihood function**.
- For arbitrary values of  $\theta$  and firms' CCPs  $\mathbf{P}$ , define:

$$Q(\theta, \mathbf{P}) = \sum_{m=1}^M \sum_{i=1}^N \sum_{t=1}^T \log \Psi_i(a_{imt} \mid \mathbf{x}_{mt}, \theta, \mathbf{P})$$

where  $\Psi_i$  is the *best response probability function*.

## MLE-NFXP with multiple equilibria [2]

- A modified version of NFXP can be applied to obtain the MLE in games with multiple equilibria.
- The MLE is the pair  $(\hat{\theta}_{MLE}, \hat{\mathbf{P}}_{MLE})$  that maximizes the  $Q$  subject to the constraint that CCPs are equilibrium strategies associated:

$$(\hat{\theta}_{MLE}, \hat{\mathbf{P}}_{MLE}, \hat{\lambda}_{MLE}) = \arg \max_{(\theta, \mathbf{P}, \lambda)} Q(\theta, \mathbf{P}) + \lambda' [\mathbf{P} - \Psi(\theta, \mathbf{P})]$$

- The F.O.C. are the Lagrangian equations:

$$\begin{cases} \hat{\mathbf{P}}_{MLE} - \Psi(\hat{\theta}_{MLE}, \hat{\mathbf{P}}_{MLE}) &= \mathbf{0} \\ \nabla_{\theta} Q(\hat{\theta}_{MLE}, \hat{\mathbf{P}}_{MLE}) - \hat{\lambda}'_{MLE} \nabla_{\theta} \Psi(\hat{\theta}_{MLE}, \hat{\mathbf{P}}_{MLE}) &= \mathbf{0} \\ \nabla_{\mathbf{P}} Q(\hat{\theta}_{MLE}, \hat{\mathbf{P}}_{MLE}) - \hat{\lambda}'_{MLE} \nabla_{\mathbf{P}} \Psi(\hat{\theta}_{MLE}, \hat{\mathbf{P}}_{MLE}) &= \mathbf{0} \end{cases}$$



## MLE-NFXP with multiple equilibria [3]

- A Newton method can be used to obtain a root of this system of Lagrangian equations.
- A key computational problem is the very high dimensionality of this system of equations.
- The most costly part of this algorithm is the calculation of the Jacobian matrix  $\nabla_{\mathbf{P}}\Psi(\hat{\boldsymbol{\theta}}, \hat{\mathbf{P}})$ . In dynamic games, in general, this is not a sparse matrix, and can contain billions or trillions of elements.
- The evaluation of the best response mapping  $\Psi(\boldsymbol{\theta}, \mathbf{P})$  for a new value of  $\mathbf{P}$  requires solving for a valuation operator and solving a system of equations with the same dimension as  $\mathbf{P}$ .
- Due to serious computational issues, there are no empirical applications of dynamic games with multiple equilibria that compute the MLE, with either the NFXP or MPEC algorithms.

## Nested Pseudo Likelihood (NPL)

- Imposes equilibrium restrictions but does NOT require:
  - Repeatedly solving for MPE for each trial value of  $\theta$  (as NFXP)
  - Computing  $\nabla_{\mathbf{P}}\Psi(\hat{\theta}, \hat{\mathbf{P}})$  (as NFXP and MPEC)
- A NPL  $(\hat{\theta}_{NPL}, \hat{\mathbf{P}}_{NPL})$ , that satisfy two conditions:
  - (1) given  $\hat{\mathbf{P}}_{NPL}$ ,  $\hat{\theta}_{NPL} = \arg \max_{\theta} Q(\theta, \hat{\mathbf{P}}_{NPL})$ ;
  - (2) given  $\hat{\theta}_{NPL}$ ,  $\hat{\mathbf{P}}_{NPL} = \Psi(\hat{\theta}_{NPL}, \hat{\mathbf{P}}_{NPL})$ .
- The NPL estimator is consistent and asymptotically normal under the same regularity conditions as the MLE. For dynamic games, the NPL estimator has larger asymptotic variance than the MLE.

## Nested Pseudo Likelihood (NPL) [2]

- An algorithm to compute the NPL is the **NPL fixed point algorithm**.
- Starting with an initial  $\hat{\mathbf{P}}_0$ , at iteration  $k \geq 1$ :
  - (Step 1) given  $\hat{\mathbf{P}}_{k-1}$ ,  $\hat{\boldsymbol{\theta}}_k = \arg \max_{\boldsymbol{\theta}} Q(\boldsymbol{\theta}, \hat{\mathbf{P}}_{k-1})$ ;
  - (Step 2) given  $\hat{\boldsymbol{\theta}}_k$ ,  $\hat{\mathbf{P}}_k = \Psi(\hat{\boldsymbol{\theta}}_k, \hat{\mathbf{P}}_{k-1})$ .
- Step 1 is very simple in most applications, as it is equivalent to obtaining the MLE in a static single-agent discrete choice model.
- Step 2 is equivalent to solving once a system of linear equations with the same dimension as  $\mathbf{P}$ .
- A limitation of this fixed point algorithm is that **convergence is not guaranteed**. An alternative algorithm that has been used to compute NPL is a **Spectral Residual algorithm**.

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## 2. Two-step CCP Methods

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## Hotz-Miller CCP Method

- To avoid the computational cost of full-solution methods, simpler two-step methods have been proposed.
- Hotz & Miller (1993) was a seminal contribution on this class of methods. They show that the conditional choice values are known functions of CCPs, transition probabilities, and  $\theta$ .
- When  $\pi_i(a_{it}, \mathbf{x}_t) = h(a_{it}, \mathbf{x}_t) \theta_{\pi,i}$ :

$$v_i(a_{it}, \mathbf{x}_t) = \tilde{h}_i^{\mathbf{P}}(a_{it}, \mathbf{x}_t) \theta_{\pi,i} + \tilde{e}_i^{\mathbf{P}}(a_{it}, \mathbf{x}_t)$$

with:

$$\tilde{h}_i^{\mathbf{P}}(a_{it}, \mathbf{x}_t) = \mathbb{E} \left( \sum_{j=0}^{\infty} \beta_i^j h(a_{it+j}, \mathbf{x}_{t+j}) \mid a_{it}, \mathbf{x}_t \right)$$

$$\tilde{e}_i^{\mathbf{P}}(a_{it}, \mathbf{x}_t) = \mathbb{E} \left( \sum_{j=0}^{\infty} \beta_i^j [\gamma - \ln P_i(a_{it+j} | \mathbf{x}_{t+j})] \mid a_{it}, \mathbf{x}_t \right)$$

## Hotz-Miller CCP Method [2]

- Given this representation of conditional choice values, the pseudo likelihood function  $Q(\boldsymbol{\theta}, \mathbf{P})$  has practically the same structure as in a static or reduced form discrete choice model.
- Best response probabilities that enter in  $Q(\boldsymbol{\theta}, \mathbf{P})$  can be seen as the choice probabilities in a standard random utility model:

$$\Psi_i(a_{imt} | \mathbf{x}_{mt}, \boldsymbol{\theta}, \mathbf{P}) =$$

$$\Pr \left( a_{imt} = \arg \max_j \left\{ \tilde{h}_i^{\mathbf{P}}(j, \mathbf{x}_{mt}) \boldsymbol{\theta}_i + \tilde{e}_i^{\mathbf{P}}(j, \mathbf{x}_{mt}) + \varepsilon_{it}(j) \right\} \right).$$

- Given  $\tilde{h}_i^{\mathbf{P}}(\cdot, \mathbf{x}_{mt})$  and  $\tilde{e}_i^{\mathbf{P}}(\cdot, \mathbf{x}_{mt})$  and a parametric specification for the distribution of  $\varepsilon$  (e.g., logit, probit), the vector of parameters  $\boldsymbol{\theta}_i$  can be estimated as in a standard logit or probit model.

## Hotz-Miller CCP Method [3]

- The method proceeds in two steps.
- Let  $\hat{\mathbf{P}}^0$  be a consistent nonparametric estimator of true  $\mathbf{P}^0$ . The two-step estimator of  $\theta$  is defined as:

$$\hat{\theta}_{2S} = \arg \max_{\theta} Q(\theta, \hat{\mathbf{P}}^0)$$

- Under standard regularity conditions, this two-step estimator is root-M consistent and asymptotically normal.
- It can be extended to incorporate market unobserved heterogeneity (e.g., Aguirregabiria & Mira (2007); Arcidiacono & Miller (2011)).
- Monte Carlo Simulation can be used to compute present values: Bajari, Benkard, & Levin (2007).
- Limitation: Finite sample bias due to imprecise estimates of CCPs in the first step.