ECO 310: Empirical Industrial Organization

Lecture 2: Production Functions: Introduction

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Outline

- 1. Model
- Data
- **3.** What determines productivity?
- 4. Estimation: The simultaneity problem

1. Model



What is a Production Function?

- It is a function that relates the amount of physical output of a production process (Y) to the amount of physical inputs or factors of production (X).
- Estimation of PFs plays a key role in empirical questions such as:
 - Productivity growth: measurement, heterogeneity (dispersion).
 - Misallocation of inputs. How allocation of capital and labor relates to TFP.
 - Estimation Firms' Costs.
 - Technological change over time or across industries. Capital intensity. Skill labor intensity.
 - Evaluating the effects of adopting new technologies
 - Measuring learning-by-doing.



Production functions

• A general representation is:

$$Y = A f(X_1, X_2, ..., X_J)$$

Y is a measure of firm output;

 $X_1, X_2, ...,$ and X_J are measures of J firm inputs;

A represents the firm's **Total Factor Productivity**.

- The marginal productivity of input j is: $MP_j = \frac{\partial Y}{\partial X_j} = A \frac{\partial f}{\partial X_j}$.
- Note that TFP increases proportionally the MP of all the inputs. We say that TFP is (Hicks) neutral.



Cobb-Douglas PF

A common specification is the Cobb-Douglas PF:

$$Y = A X_1^{\alpha_1} X_2^{\alpha_2} \dots X_J^{\alpha_J}$$

 $\alpha_1, \alpha_2, ..., \alpha_J$ are technological parameters (all positive).

• For the Cobb-Douglas PF the marginal productivity of input j is:

$$MP_j = \alpha_j \frac{Y}{X_j}$$

• All the inputs are complements in production. MP_j increases with the amount of any other input k:

$$\frac{\partial MP_j}{\partial X_k} = \frac{\alpha_j}{X_j} \frac{\alpha_k}{X_k} Y > 0$$



Production function and Cost Function

Given the production function and input prices, the cost function
 C(Y) is defined as the minimum cost of producing the amount of
 output Y:

$$C(Y) = \begin{bmatrix} \min_{\{X_1, X_2, ..., X_J\}} W_1 X_1 + W_2 X_2 + ... + W_J X_J \\ \text{subject to: } Y = A \ f(X_1, X_2, ..., X_J) \end{bmatrix}$$

• Or using a Lagrange representation:

$$C(Y) = \min_{\{\lambda, X_1, ..., X_J\}} W_1 X_1 + ... + W_J X_J + \lambda [Y - A f(X_1, ..., X_J)]$$

where λ is the Lagrange multiplier of the restriction.

ullet The marginal conditions of optimality imply that for every input j,

$$W_j - \lambda MP_j = 0$$

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Cost Function: Cobb-Douglas

• For the Cobb-Douglas PF $Y = A X_1^{\alpha_1} ... X_1^{\alpha_j}$ the marginal condition of optimality for input j implies:

$$W_j X_j = \lambda \alpha_j Y$$

• Therefore, the cost is equal to:

$$\sum_{j=1}^{J} W_j X_j = \lambda \alpha Y$$

where $\alpha \equiv \sum_{j=1}^{J} \alpha_j$ and measures returns to scale: constant if $\alpha = 1$, decreasing if $\alpha < 1$, and increasing if $\alpha > 1$.

• We need to obtain the value of the Lagrange multiplier λ . For this, we solve the marginal conditions $X_i = \lambda \alpha_i Y/W_i$ into the PF:

$$Y = A \left(\frac{\lambda \alpha_1 Y}{W_1}\right)^{\alpha_1} \left(\frac{\lambda \alpha_2 Y}{W_2}\right)^{\alpha_2} \dots \left(\frac{\lambda \alpha_J Y}{W_J}\right)^{\alpha_J}$$

Cost Function: Cobb-Douglas (2)

• Solving in this expression for the Lagrange multiplier:

$$\lambda = \left(\frac{W_1}{\alpha_1}\right)^{\frac{\alpha_1}{\alpha}} \left(\frac{W_2}{\alpha_2}\right)^{\frac{\alpha_2}{\alpha}} \dots \left(\frac{W_J}{\alpha_J}\right)^{\frac{\alpha_J}{\alpha}} \left(\frac{Y}{A}\right)^{\frac{1}{\alpha}} \frac{1}{Y}$$

• Plugging the expression of the multiplier into the equation $\lambda \alpha Y$ for the cost, we obtain the cost function:

$$C(Y) = \alpha \left(\frac{Y}{A}\right)^{\frac{1}{\alpha}} \left(\frac{W_1}{\alpha_1}\right)^{\frac{\alpha_1}{\alpha}} \left(\frac{W_2}{\alpha_2}\right)^{\frac{\alpha_2}{\alpha}} \dots \left(\frac{W_J}{\alpha_J}\right)^{\frac{\alpha_J}{\alpha}}$$

• The sign of C''(Y) is equal to the sign of $\frac{1}{\alpha} - 1$.

$$\alpha = 1$$
 (constant returns): $C''(Y) = 0$ (linear)

$$\alpha < 1$$
 (decreasing returns): $C''(Y) > 0$ (convex)

$$\alpha > 1$$
 (increasing returns): $C''(Y) < 0$ (concave).



More on the Cobb-Douglas

 A nice property (for estimation) of the Cobb-Douglas is that its logarithm transformation is linear in parameters:

$$ln(Y) = ln(A) + \alpha_1 ln(X_1) + \alpha_2 ln(X_2) + ... + \alpha_J ln(X_J)$$

• We will represent $\log(Y)$ and $\log(X)$ using the lower letters y and x, resp., and the log-TFP using ω , such that:

$$y = \omega + \alpha_1 x_1 + \alpha_2 x_2 + ... + \alpha_J x_J$$

- ullet Differences in log-TFP (ω) are in percentage terms:
 - Consider two firms, 1 and 2, using the same amount of inputs X but with $\omega_1=1.1$ and $\omega_2=1.5$ such that $\omega_2-\omega_1=0.4$. Therefore, firm 2 is 40% more productive than firm 1.



More on the Cobb-Douglas (2)

 Most empirical applications that we will see in the course consider two inputs: labor (L) and capital (K):

$$y = \alpha_L \ \ell + \alpha_K \ k + \omega$$

with $\ell \equiv \ln(L)$ and $k \equiv \ln(K)$.

Sometimes the specification also includes materials (M):

$$y = \alpha_L \ \ell + \alpha_K \ k + \alpha_M \ m + \omega$$

with $m \equiv \ln(M)$.



2. Data



Data

 Panel data of N firms over T periods with information on output, labor, and capital (in logs):

$$\{ y_{it}, \ell_{it}, k_{it} : i = 1, 2, ..., N ; t = 1, 2, ...T \}$$

We are interested in the estimation of the Cobb-Douglas PF (in logs):

$$y_{it} = \alpha_L \ell_{it} + \alpha_K k_{it} + \omega_{it} + e_{it}$$

 $\omega_{it} = log\text{-}TFP$. Unobserved inputs (for the researcher) which are known to the firm when it decides K and L (e.g., managerial ability, quality of land, different technologies).

 e_{it} = measurement error in output or shock affecting output that is unknown to the firm when it decides K and L.



Measurement: Observing revenue instead of physical output

- $R_{it} = P_{it} Y_{it}$ such that $\ln(R_{it}) = \ln(P_{it}) + y_{it}$, but the researcher only observes $\ln(R_{it})$.
- Possible solution: Try to measure $ln(P_{it})$ as good as possible using industry level price indexes.
- Possible solution: Assume monopolistic competition and isoelastic demand: $y_{it} = b_{it} \beta \ p_{it}$, where β is the elasticity of demand, such that:

$$\ln(R_{it}) = \frac{b_{it}}{\beta} + \left(1 - \frac{1}{\beta}\right) y_{it} = \alpha_L^* \ \ell_{it} + \alpha_K^* \ k_{it} + \omega_{it}^* + e_{it}$$

with
$$lpha_L^*=\left(1-rac{1}{eta}
ight)lpha_L$$
, $lpha_K^*=\left(1-rac{1}{eta}
ight)lpha_K$, and $\omega_{it}^*=\omega_{it}+rac{b_{it}}{eta}$.

• Relevant for interpretation of results and of "log-TFP".

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Measurement: Capital

- We typically observe firms' investments in physical capital but not the capital stock K_{it} .
- Instead we observe the "book value" (accounting value) of capital and of amortization.
- The most common approach to construct the economic stock of capital is the perpetual inventory method.

$$K_{it} = (1 - \delta) K_{it-1} + I_{it}$$

such that:

$$K_{it} = I_{it} + (1 - \delta)I_{it-1} + ... + (1 - \delta)^{t-1}I_1 + (1 - \delta)^t K_0$$

• We know investments. We need to know the depreciation rate (δ) and the initial capital stock (K_0) .



3. What determines productivity?

Total Factor Productivity (TFP)

• Production function:

$$Y_{it} = A_{it} F(K_{it}, L_{it}, M_{it})$$

- A_{it} is denoted Total Factor Productivity (TFP).
- It is a factor-neutral shifter that captures variations in output not explained by observable inputs.
- TFP is a residual.

Large and persistent differences in TFP across firms

- Ubiquitous, even within narrowly defined industries and products.
- Large: 90th to 10th percentile TFP ratios: $\frac{A_{90th}}{A_{10th}}$
 - U.S. manufacturing, average within 4-digit \tilde{SIC} industries = 1.92 (Syverson, 2004)
 - Denmark: average = 3.75 (Fox and Smeets, 2011)
 - China or India, **average** > **5** (Hsieh & Klenow, 2009).
- Persistent:
 - AR(1) of log-TFP with annual frequency: autoregressive coefficients between 0.6 to 0.8.
- It matters: Higher productivity producers are more likely to survive.

Why firms differ in their productivity levels?

- What supports such large productivity differences in equilibrium?
- Can producers control the factors that influence productivity or are they purely external effects of the environment?
- If firms can partly control their TFP, what type of choices increase it?

Why dispersion is possible in equilibrium?

• Let the profit of a firm be:

$$\pi_i = P_i(Y_i) Y_i - C(Y_i, A_i) - F$$

 $P_i(Y_i)$ = Inverse demand function. $C(Y_i, A_i)$ = Cost function. F = fixed costs.

- **Key condition:** either $P_i(Y_i)$ Y_i is strictly concave in Y_i , or C(.) is strictly convex in Y_i . [The profit function is strictly concave].
- Example: Perfect competition. $P Y_i$ is linear in Y_i . We need C(.) to be strictly convex. i.e., DRS in variable inputs.
- Example: Monopolistic or Cournot competition. $P_i(Y_i)$ Y_i is strictly concave in Y_i , (downward sloping demand). So we can have either CRS or DRS.

Why dispersion is possible in equilibrium? [2]

• Equilibrium implies the marginal condition for optimal output:

$$MR_i \equiv \frac{\partial [P(Y_i) Y_i]}{\partial Y_i} = \frac{\partial C(Y_i, A_i)}{\partial Y_i} \equiv MC_i$$

- If variable profit is strictly concave, this equilibrium can support firms with different TFPs, A_i .
- It is not optimal for the firm with highest TFP to provide all the output in the industry.
- Firms with different TFPs (above a certain threshold value) operate in the same market.

How can a firm affect its TFP?

- (HR) Managerial Practices. (Bloom & Van Reenen, 2007; Ichniowski and Shaw, 2003)
- Learning-by-Doing (Benkard, 2000).
- Organizational structure (vertical integration vs outsourcing).
- Higher-Quality (Labor and Capital) inputs.
- Adoption of new (IT) technologies. (Brynjolfsson et al., 2008).
- Investment in R&D. Long literature linking R&D investment and productivity.
- Innovation. Many firms undertake both process and product innovation without formally reporting R&D spending.

4. Estimation: Endogeneity / Simultaneity Problem

Endogeneity / Simultaneity problem

Consider the PF:

$$y_{it} = \alpha_L \ell_{it} + \alpha_K k_{it} + \omega_{it} + e_{it}$$

- We are interested in the estimation of α_L and α_K . These parameters represent "ceteris paribus" causal effects of labor and capital on output, respectively.
- When the manager decides the optimal (k_{it}, ℓ_{it}) she has some information about log-TFP ω_{it} (that we do not observe).
- This means that there is a correlation between the observable inputs (k_{it}, ℓ_{it}) are correlated with the unobservable ω_{it} .
- This correlation implies that the OLS estimators of α_L and α_K are biased and inconsistent.

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